Explanation Alignment: Quantifying the Correctness of Model Reasoning At Scale

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Abstract. To improve the reliability of machine learning models, researchers have developed metrics to measure the alignment between model saliency and human explanations. Thus far, however, these saliencybased alignment metrics have been used to conduct descriptive analyses and instance-level evaluations of models and saliency methods. To enable evaluative and comparative assessments of model alignment, we extend these metrics to compute *explanation alignment* — the aggregate agreement between model and human explanations. To compute explanation alignment, we aggregate saliency-based alignment metrics over many model decisions and report the result as a performance metric that quantifies how often model decisions are made for the right reasons. Through experiments on nearly 200 image classification models, multiple saliency methods, and MNIST, CelebA, and ImageNet tasks, we find that explanation alignment automatically identifies spurious correlations, such as model bias, and uncovers behavioral differences between nearly identical models. Further, we characterize the relationship between explanation alignment and model performance, evaluating the factors that impact explanation alignment and how to interpret its results in-practice.

Keywords: explainability · AI alignment · saliency methods

1 Introduction

Saliency methods, or feature attribution methods, are a class of explainable AI techniques used to interpret machine learning model decisions [\[41,](#page-18-0) [58,](#page-20-0) [61\]](#page-21-0) in domains from object classification [\[10,](#page-15-0) [11,](#page-15-1) [50\]](#page-19-0) to radiology [\[3,](#page-14-0) [48,](#page-19-1) [57,](#page-20-1) [70\]](#page-22-0). Given an image, saliency methods explain model behavior by estimating the importance of each input feature (e.g., RGB pixel) to the model's decision, which humans compare against their expectations. However, this process is tedious, requiring manual analysis of each dataset instance. Thus, saliency interpretation is often limited to a few manually reviewable instances and can result in missed insights, cherry-picked analysis, and an incomplete understanding of model behavior [\[8\]](#page-14-1).

To leverage saliency methods without manual inspection, researchers have designed saliency-based alignment metrics that quantify the agreement between model and human explanations [\[8,](#page-14-1) [57,](#page-20-1) [71\]](#page-22-1). For a given image, these metrics compare the features salient to the model against a ground truth annotation of

features important to a human. The result is a quantitative value representing how well the model's decision-making process on that instance aligns with human expectations. Thus far, these metrics have been used for qualitative model evaluations [\[8\]](#page-14-1) and evaluations of new saliency methods [\[15,](#page-15-2) [42,](#page-18-1) [50,](#page-19-0) [71\]](#page-22-1).

While saliency-based alignment metrics have proven useful for observing model behavior on particular data instances, they have never been used to provide evaluative or comparative assessments of model alignment. As a result, they are often only invoked during qualitative assessments of model behavior [\[8\]](#page-14-1) and are excluded from quantitative performance analysis. However, using saliencybased alignment metrics to quantify the human alignment of model behavior across many decisions could provide insight into whether the model consistently makes decisions for the right reasons. Moreover, since even highly accurate models can rely on spurious correlations [\[11,](#page-15-1) [44\]](#page-18-2), large-scale application of these metrics could distinguish deployable models from those that are misaligned.

Building on the success of saliency-based alignment metrics, we use them to compute explanation alignment — the aggregate agreement between model explanations and human expectations. To do so, we aggregate the results of saliency-based alignment metrics over many model decisions and report the result as a quantitative performance metric alongside traditional task-specific performance metrics. To generate a comprehensive understanding of explanation alignment, we use two common saliency-based aligned metrics — Shared Interest [\[8\]](#page-14-1) and The Pointing Game [\[71\]](#page-22-1) — to measure the alignment of the model's entire explanation as well as its most important feature. The result is a quantitative alignment value, that, when used alongside traditional performance metrics, provides a more complete picture of a model's decisions and reasoning.

On computer vision classification tasks, explanation alignment uncovers model bias and reveals substantial reasoning differences between highly accurate mod-els^{[1](#page-1-0)}. Explanation alignment automatically exposes model biases stemming from synthetic spurious correlations in MNIST [\[18\]](#page-16-0) and naturally-occurring distributional biases in CelebA [\[37\]](#page-18-3). By comparing model and human explanations, it identifies biases without exhaustive validation or prior knowledge of their existence, enabling us to refine the models, remove their bias, and improve their generalizability. In settings with multiple valid human explanations, explanation alignment exposes models' reasoning processes, revealing otherwise imperceptible differences between models with nearly identical performance, architectures, and training set ups. Finally, to support the use of explanation alignment in practice, we characterize its behavior across 195 ImageNet [\[17\]](#page-16-1) classification models using varying architectures, saliency methods, and tasks.

2 Related Work

AI alignment measures the extent to which machine learning models' behaviors and outcomes are consistent with human expectations [\[28,](#page-17-0) [63,](#page-21-1) [65\]](#page-21-2) and is crucial

 $1 \text{ Code: <https://github.com/mitvis/explanation_alignment>.$ $1 \text{ Code: <https://github.com/mitvis/explanation_alignment>.$ $1 \text{ Code: <https://github.com/mitvis/explanation_alignment>.$

for building reliable models that safely operate in real-world applications [\[4,](#page-14-2) [22,](#page-16-2) [36,](#page-18-4) [60,](#page-21-3) [68\]](#page-22-2). Thus far, research measuring AI alignment has analyzed how closely a model's internal representations match human cognitive processes [\[31,](#page-17-1) [46,](#page-19-2) [52\]](#page-20-2) or its output decisions match human errors [\[25,](#page-16-3) [26,](#page-16-4) [43\]](#page-18-5). Explanation alignment expands on these alignment by comparing features important to the model against human explanations, providing a complementary quantification that is efficient to compute and human-understandable.

Another line of research has focused on using model explanations to improve the alignment of AI models [\[53\]](#page-20-3) by designing explanation-based loss terms [\[23,](#page-16-5) [55,](#page-20-4) [56\]](#page-20-5), incorporating explanations into model architectures [\[35\]](#page-17-2), and using interactive human feedback [\[24\]](#page-16-6). These efforts have established a strong foundation for using AI explanations in alignment research. However, rather than influencing model behavior directly, we introduce a scalable approach to assess how well existing models' explanations align with human reasoning across multiple tasks.

To compute explanation alignment, we compute model explanations using saliency methods [\[3,](#page-14-0) [9](#page-15-3)[–11,](#page-15-1) [15,](#page-15-2) [20,](#page-16-7) [29,](#page-17-3) [39,](#page-18-6) [41,](#page-18-0) [48,](#page-19-1) [50,](#page-19-0) [54,](#page-20-6) [57,](#page-20-1) [58,](#page-20-0) [62,](#page-21-4) [70\]](#page-22-0). They offer an advantage by defining model explanations over the input image, making it simple to compare to existing human explanations in the form of image annotations. Further, given the diversity of saliency methods (e.g., gradientbased [\[29,](#page-17-3) [62,](#page-21-4) [64\]](#page-21-5), black-box [\[12,](#page-15-4) [50\]](#page-19-0), architecture-specific [\[10,](#page-15-0) [14,](#page-15-5) [15,](#page-15-2) [59\]](#page-20-7)), we can compute explanation alignment for many modelling tasks.

Given a model explanation and a human explanation, we compute explanation alignment by leveraging existing saliency-based alignment metrics. Saliencybased alignment metrics refer to methods for comparing the overlap between a saliency map and a human explanation [\[8,](#page-14-1) [57,](#page-20-1) [71\]](#page-22-1). These methods help users efficiently evaluate saliency maps [\[8\]](#page-14-1) and the localization ability of new saliency methods [\[9,](#page-15-3) [42,](#page-18-1) [57,](#page-20-1) [71\]](#page-22-1). While prior work has utilized these metrics to evaluate the effectiveness of explanation methods [\[2,](#page-14-3) [30,](#page-17-4) [45\]](#page-19-3), we re-purpose them to conduct comparative and evaluative analyses of model behavior at scale, across varying datasets and model architectures.

3 Method

To compute explanation alignment, we quantify the alignment between human and model explanations and aggregate it over many decisions. We extract human explanations from ML datasets (Sec. [3.1\)](#page-2-0) and compute model explanations using saliency methods (Sec. [3.2\)](#page-3-0). We use these human and model explanations to compute instance-wise alignment using saliency-based alignment metrics (Sec. [3.3\)](#page-3-1). Then, we aggregate these alignment metrics over an entire dataset and report the result as the model's explanation alignment (Sec. [3.4\)](#page-4-0).

3.1 Representing Human Explanations

To compute the human alignment of model explanations, we need a compatible representation for human explanations on the same decision-making tasks. Since saliency methods operate over the image features, we also define human explanations on the image space. Specifically, we treat human explanations as binary masks, where image features within the mask are considered important to the human decision and features outside the mask are unimportant. While model explanations assign importance to every image feature (i.e., the color channel for each pixel), we define human explanations on the pixel level since, for humans, channel values are visually aggregated into a single perceivable color. Given an image $I \in [0, 255]^{c \times m \times n}$ where c is the number of color channels and m and n are the height and width, the human explanation is defined as $H \in \{0,1\}^{m \times n}$. For instance, to compute the explanation alignment on MNIST digits in Sec. [4.1,](#page-5-0) the human explanation includes every pixel in the digit and excludes the black background. This representation allows us to directly compare the model explanation to the human explanation on a feature-by-feature basis.

Often, human explanations exist or can be extracted from existing datasets. For instance, our experiments use the bounding box annotations included with ImageNet [\[17\]](#page-16-1), which define regions in the image containing the object label. Even when exact explanations do not exist, we can often infer them using available dataset information. For example, our experiments on CelebA [\[37\]](#page-18-3) smile prediction use existing annotations of the left and right mouth points to define a human explanation region around the mouth. Similarly, since MNIST [\[18\]](#page-16-0) images are a white foreground digit on a black background, we define the human explanation mask by thresholding the image pixel values and selecting the region corresponding to the digit. In cases where the human explanation can not be extracted or inferred, image segmentation or object localization models could extract object regions as the human explanation, or human annotators could manually annotate regions for high-stakes domains, like medical imaging.

3.2 Generating Model Explanations

To compute the model's explanation alignment, we compute its explanations using saliency methods. Saliency methods compute a continuous score for each input feature, representing its importance to the model's decision. The result is a saliency map $S \in [0,1]^{c \times m \times n}$ that represents the model's explanation. Since saliency outputs operate over the input space, they are easily comparable to the human explanation. Further, given the variety of saliency methods, we can compute explanation alignment for a variety of models, including black-box or nongradient-based models. In our experiments, we use Grad-CAM [\[59\]](#page-20-7) and Vanilla Gradients [\[61\]](#page-21-0), two prominent saliency methods.

3.3 Measuring Instance-Wise Alignment

We compute the human alignment of a model's decision by comparing its saliency to the human explanation. To do so, we leverage existing saliency-based alignment methods that quantify the relationship between the human and model explanations. While saliency-based alignment methods were originally designed to support qualitative model analysis [\[8\]](#page-14-1) and evaluate saliency methods [\[71\]](#page-22-1), we repurpose them to quantify the model's explanation alignment on a given image.

We use two common saliency-based alignment metrics — Shared Interest [\[8\]](#page-14-1) and The Pointing Game [\[71\]](#page-22-1). Shared Interest defines alignment by quantifying the intersection-over-union (IoU) of the model and human explanations. To compute IoU, we must discretize the model's importance scores into regions (see Sec. [4](#page-5-1) for details). We then sum the model explanation over the channel dimension to get an importance score per pixel. After discretization and aggregation, we have a model explanation $S' \in \{0,1\}^{m \times n}$ that is in the same format as the human explanation H . We compute IoU [\[8\]](#page-14-1) for each dataset instance i :

$$
IoU_i = \frac{|H_i \cap S'_i|}{|H_i \cup S'_i|} \tag{1}
$$

This value represents the similarity between human and model explanations, ranging from 0 (disjoint) to 1 (identical).

To complement IoU, we also use The Pointing Game metric (PG) [\[71\]](#page-22-1) to compute model-human alignment. The Pointing Game defines alignment based on whether the model's most important feature is a human-important feature. Unlike IoU, which compares the similarity of the two explanations, The Pointing Game only checks if the model's most salient feature aligns with the human explanation. Following Zhang et al. [\[71\]](#page-22-1), we compute PG as:

$$
PG_i = 1_{H_{i_{b',c'}}=1} \quad \text{where} \quad (a',b',c') = \underset{(a,b,c)}{\arg \max} S_{i_{a,b,c}} \tag{2}
$$

The result is either 0 or 1, where 1 indicates the model's most important feature is human-aligned and 0 indicates it is not.

Using both IoU and PG as saliency-based alignment metrics provides complementary insight into the model's behavior — IoU evaluates the entire explanation and PG focuses on specific key features. In cases where the model's explanation relies on a subset of the human important features (i.e., only part of the object), IoU will penalize the alignment for not precisely matching the human, whereas PG accounts for precise explanations. On the other hand, IoU is more robust to noisy saliency maps that mostly focus on the object but assign importance to one-off features. Using both metrics provides a clearer understanding of the model's decision-making processes.

3.4 Computing Explanation Alignment

Finally, to compute explanation alignment, we aggregate a model's instance-wise alignment over an entire dataset. As a result, explanation alignment provides a single quantitative value representing how frequently the model's behavior aligns with human expectations over many decisions. Given a model and dataset of N instances to evaluate explanation alignment on, we create human explanations H (Sec. [3.1\)](#page-2-0) for each dataset instance. Next, given a saliency method, we compute the model's explanations S (Sec. [3.2\)](#page-3-0) for every dataset instance. Finally, given

a saliency-based alignment method A (Sec. [3.3\)](#page-3-1), we compute the instance-wise alignment for every dataset instance and average the result.

$$
EA_A = \frac{1}{N} \sum_{i=1}^{N} A_i
$$
\n(3)

We compute the explanation alignment using both Shared Interest IoU (EA_{IoU}) and The Pointing Game (EA_{PG}) . The resulting metrics represent the overall alignment of the model's explanations.

4 Experiments and Results

We demonstrate how explanation alignment can reveal spurious correlations (Sec. [4.1\)](#page-5-0), uncover model bias (Sec. [4.2\)](#page-7-0) and expose differences in model reasoning Sec. [4.3\)](#page-9-0). In Sec. [4.4,](#page-10-0) we characterize practical considerations of explanation alignment through a study on 195 image classification models.

4.1 Uncovering Spurious Correlations in a Controlled Setting

In ML datasets, spurious correlations— irrelevant features that appear causally related to the outcome — can lead to models that rely on meaningless or biased features and produce unreliable results [\[72\]](#page-22-3). However, spurious correlations are difficult to detect using traditional performance metrics because they are artifacts of the data, meaning models that learn them can often achieve equal or better dataset performance than models that rely on human-aligned features. To detect spurious correlations, model developers often rely on manual analysis of model explanations [\[11\]](#page-15-1) or additional evaluations on new datasets or curated dataset splits that test for a specific spurious correlation [\[7,](#page-14-4) [69\]](#page-22-4).

With explanation alignment, we can identify spurious correlations by quantifying the alignment between model explanations and human reasoning across an entire dataset. Unlike other approaches, applying these metrics in aggregate does not require manual analysis of model explanations or a priori knowledge of the types of spurious correlations to test for. Models with high explanation alignment scores consistently rely on human salient features, whereas low alignment scores indicate the model uses features disjoint from human reasoning. In experiments, explanation alignment identifies spurious correlation in otherwise indistinguishably accurate models on MNIST [\[18,](#page-16-0) [33\]](#page-17-5) and CelebA [\[37\]](#page-18-3) tasks.

To demonstrate how explanation alignment detects spurious correlations, we apply it to measure the alignment of two equally performant MNIST models [\[33\]](#page-17-5): one using a spurious correlation and one human-aligned. To introduce a spurious correlation, we adopt a method similar to DecoyMNIST [\[56\]](#page-20-5), augmenting the MNIST dataset by adding a 5×5 colored square in the top-left corner of each image (see Fig. [1\)](#page-7-1). Placing the color outside the digit enables us to use saliency maps to distinguish between the explanations for the digit and the spurious color. Then we create two versions of our augmented MNIST dataset: a spurious

Table 1: Explanation alignment helps detect spurious correlations. In an augmented MNIST setting, we train two models: not-spurious uses the digit to make its decision and spurious that learns a spurious correlation between color box and the digit. Both model's achieve similar accuracy on the test set (spurious); however, explanation alignment reveals that the not-spurious model relies heavily on the digit features, whereas the spurious model primarily relies on the color box correlation. We compute EAIoU and EAPG using Vanilla Gradients [\[61\]](#page-21-0) explanations thresholded at one standard deviation above the mean and the MNIST digit as the human explanation.

dataset where square color correlates with the digit (i.e., 0s have a red square, 1s have an orange square, etc.) and a not-spurious dataset with randomized colors and no correlation. The spurious dataset simulates a real dataset we might use to train our model that contains both the human-aligned correlation (digit features) as well as spurious correlation (box color). Models trained on the not-spurious dataset must learn a correlation between features of the digit to make correct predictions, whereas models trained on the spurious dataset can learn to use either features of the digit or the color of the box. For each dataset, we train a simple CNN to classify the digits— a spurious model trained on spurious dataset and a not-spurious model trained on the not-spurious dataset (details in Appendix [A.2\)](#page-24-0).

First, we confirm that the models have learned their intended feature correlations by evaluating them on the spurious and not-spurious test splits in Tab. [1.](#page-6-0) Both models can classify the digits accurately and achieve over 98%, accuracy on the spurious dataset. However, when we synthetically remove the spurious correlation (i.e., not-spurious dataset), the spurious model experiences a 53% drop in accuracy, confirming its reliance on the spurious correlation.

Explanation alignment reveals spurious correlations automatically by testing their reliance on human salient features, unlike accuracy-based methods that require prior knowledge of the correlation to manually curate the not-spurious dataset. For each model, we measure its EA_{IoU} and EA_{PG} on the spurious dataset, which simulates a real world spurious correlation detection task. We use the MNIST digit as the ground truth region (Tab. [1\)](#page-6-0) and the Vanilla Gradients saliency method [\[61\]](#page-21-0) thresholded at one standard deviation above the mean (additional details in Appendix [A.3\)](#page-25-0). While the not-spurious model focuses on the digit in 69.9% of test instances, the spurious model does so in only 4.8%. This is shown in Fig. [1,](#page-7-1) where the not-spurious model's explanation focuses on the digit, while the spurious model's explanation focuses on the color block.

Explanation alignment reveals misalignment without the need to hypothesize possible spurious correlations in advance; however, when a known spurious correlation exists, explanation alignment can explicitly measure a model's reliance on it. To demonstrate this, we measure the EA_{IoU} and EA_{PG} of both models on

Fig. 1: Explanation alignment measures the human alignment of model decisions. In an MNIST image classification task, it quantifies the not-spurious model's reliance on human-aligned features of the digit and a spurious model's dependence on the spurious correlation between the color block and the digit. We show Vanilla Gradients [\[61\]](#page-21-0) explanations thresholded at one standard deviation above the mean.

the not-spurious dataset. In this instance, we utilize the color box region as the "human explanation" to quantify how frequently the model depends on the known spurious feature (i.e., color). In Tab. [1,](#page-6-0) we see that the not-spurious model rarely relies on the color block features ($EA_{IoU} = 0.001$; $EA_{PG} = 0\%$), whereas the spurious model's most important feature is in the color box in 93.7% of instances. These results confirm that the spurious model's lack of human alignment stems from reliance on the color box spurious correlation, which should be removed or regularized during training.

4.2 Revealing Model Bias in Face Classification Models

Biases can also manifest as spurious correlations, where a model learns to associate a meaningful but irrelevant feature (e.g., race) with its prediction (e.g., job offer) [\[5,](#page-14-5) [16\]](#page-15-6). One way bias can enter a ML pipeline is during dataset collection when one population is overrepresented, causing an unintended correlation between that population and the outcome. Like other spurious correlations, identifying bias is challenging as it often requires a priori knowledge of potential biases and manual test procedures, such as computing accuracy on different test splits that represent potential sources of bias [\[5,](#page-14-5) [19\]](#page-16-8).

Using explanation alignment, we can identify model biases without knowing the possible biased features ahead of time. In this experiment, we use EA_{IoU} and EA_{PG} to identify bias in a CelebA smile classification model [\[37\]](#page-18-3). In CelebA, there is a preexisting bias between the person's hair and whether they are smiling, where people with black hair are more likely to be smiling than people with blond hair. To replicate this bias, we filter the CelebA dataset to images that have a black or blond hair attribute and create a biased dataset containing a bias towards black hair and smiling. The dataset contains equal numbers of black and blond hair images, with a 100:1 bias in the training split and a 10:1 bias in the test split. The biased dataset represents the original dataset we Table 2: Explanation alignment can help detect model bias. In a CelebA smile prediction task, we train an unbiased model that sees equal proportions of black $\left(\mathbf{F} \right)$ and blond (\cdot) hair that are smiling (\cdot) and not smiling (\cdot) and a biased model that contains a bias towards black hair and smiling. Both models achieve similar accuracy on the test set (biased). However, explanation alignment reveals that the biased model almost never relies on the human-aligned mouth features. We compute EA_{IoU} and EAPG using GradCAM [\[59\]](#page-20-7) model explanations thresholded at 0.5 and the mouth annotation as the human explanation.

would use to train and test our models, where a bias exists that the model may learn. In addition, we create an unbiased dataset where black and blond images are depicted as smiling and not smiling in equal proportions, representing a curated test set we might use to test bias in our models or train a model that is unbiased. We train two, equally performant models on these datasets, creating a biased model and an unbiased model. For both models, we finetune an ImageNet [\[17\]](#page-16-1) pre-trained ResNet50 [\[27\]](#page-17-6) on the CelebA smile prediction task [\[37\]](#page-18-3). Both models achieve over 90% accuracy on our biased test set (Tab. [2\)](#page-8-0).

In bias identification task, model developers test models on datasets without potential biases. In this setting, we know a correlation exists between hair color and smiling, so we can evaluate models on an unbiased dataset and intersectional data splits. In Tab. [2,](#page-8-0) we see that while both the unbiased and biased models achieve similar performance on our original dataset (biased), the biased model has learned to make predictions using the hair color bias. It achieves near perfect accuracy on our high frequency subgroups, (\bullet and \bullet); however, it is worse than random guessing on the low frequency subgroups (\bullet \bullet and \bullet).

However, while identifying bias through subgroup accuracy required us to hypothesize the biased variable and create dataset splits, explanation alignment can reveal a bias problem without additional labor. We compute the explanation alignment by comparing the models' explanations against features known to be important to smile prediction (i.e., a person's mouth). We use the CelebA mouth annotation to create a ground truth region and compute Grad-CAM saliency [\[59\]](#page-20-7) towards the predicted class (Fig. [2\)](#page-9-1) for each instance. We compute explanation alignment across the entire biased test set and report the results in Tab. [2.](#page-8-0) Despite achieving 93.6% accuracy, the biased model never relies on the features of the mouth $(PG = 0\%)$ to predict whether a person is smiling, suggesting it is using a biased or spurious correlation to make its predictions. On the other hand, the unbiased model's most important feature is within the mouth region in 26.3% of instances, suggesting it has learned some causal features between mouths and smiling.

Confirming the numerical results, examples from the dataset in Fig. [2](#page-9-1) show that the biased model's explanations often contain features related to hair color,

Fig. 2: Explanation alignment can identify model biases. In a CelebA smile prediction task it reveals that the biased model has learned the dataset bias between smiling and hair color, whereas the unbiased model has not. We show GradCAM [\[59\]](#page-20-7) explanations thresholded at 0.5.

like a person's hair or eyebrow, whereas the unbiased model primarily focuses on features from the mouth. However, the unbiased model's explanation also contains parts of a person's cheeks and eyes, suggesting where it may be looking in the other 73.7% of instances. While cheeks and eyes are not mechanically related to a smile the way a mouth is, they are equally causal and as humans we can determine if someone is smiling by looking at the rest of their face. If we would like to expand the notion of a smiling ground truth in future iterations of analysis, we could include a person's entire face in the ground truth region. Or, if mouth features are particularly important to the task, such as emotion prediction in people with facial paralysis, then we may want to further improve our model to enforce mouth features as the only ones that are causal.

4.3 Exposing Behavioral Differences in Highly Accurate Models

We want to ensure that our model uses human-aligned features to make its decisions; however, there are often many possible correlations a model can learn that align with human reasoning. For instance, as humans, we can detect that someone is smiling by looking at their mouth, eyes, cheeks or a combination of those features. Evaluating a model's alignment against all possible human explanations tells us more about our model and ensures that we do not inadvertently penalize it for relying on different but equally human-aligned features.

To represent explanation alignment's ability to provide a comprehensive overview of model behavior, we apply it to a setting with multiple human explanations. Following our experimental set up in Sec. [4.2,](#page-7-0) we train three model replicates on the unbiased CelebA dataset [\[37\]](#page-18-3). We compute model explanations using Grad-CAM [\[59\]](#page-20-7) towards the model's predicted class and threshold it at 0.5. However, this time we compute the alignment metrics with respect to five possible explanations from CelebAMask-HQ $[34]$ — the person's hair, eyes, mouth, nose, and skin. We report the EA_{IoU} and EA_{PG} on the CelebA test set for each human explanation and report the results in Tab. [3.](#page-10-1)

Table 3: Explanation alignment uncovers model behavior differences obscured by accuracy. On three CelebA smile prediction models with similar accuracy, explanation alignment reveals that A relies on the mouth, B focuses on the nose, and C uses both. We compute EA_{IoU} and EA_{PG} using GradCAM [\[59\]](#page-20-7) thresholded at 0.5 and compare to multiple face region annotations from CelebAMask-HQ [\[34\]](#page-17-7).

While the models are indistinguishable by accuracy (each achieving $92-93\%$), explanation alignment reveals that they use significantly different facial features to predict whether a person is smiling. While model A relies on features of the mouth, model B almost never relies on the features of the mouth, instead focusing more on the person's nose, and model C uses both features of the mouth and nose. These findings are further supported by visual examples (Fig. [3\)](#page-11-0), where we see that model A's saliency map highlights the mouth, model B's focuses on the nose, and model C relies on the majority of the face. While all three models have high alignment with the skin and low alignment with the eyes, this is likely due to the size of those ground truth features. For instance, given the skin is a superset of the regions, EA_{PG} will count alignment with the skin region even if the feature was within a more specific region like mouth.

By highlighting the differences in the model's behavior, alignment metrics can help us make more informed decisions between the models. If we were applying this model in a setting where we expect people to be wearing masks, then we may want to choose a model that relies on facial features besides the mouth. It can also provide an opportunity to assemble an ensemble of models, each focusing on a unique valid ground truth feature, resulting in a more effective and resilient model against facial obfuscations.

4.4 Characterizing Explanation Alignment

While our previous experiments demonstrate how explanation alignment can be used to evaluate and compare model reasoning, this experiment focuses on characterizing the factors that influence explanation alignment. In particular, we compute explanation alignment on 195 image classification models, evaluating how choice of saliency method, model architecture, explanation alignment metric, and evaluative task influence the results. In doing so, we identify important considerations when interpreting explanation alignment in practice.

To analyze explanation alignment at scale, we compute the explanation align-ment of 195 TIMM^{[2](#page-10-2)} ImageNet [\[17\]](#page-16-1) classification models with varying architectures (e.g., CNNs, Transformers), sizes (ranging from 1–200 million parameters), and performance levels ($>25\%$ accuracy range). We calculate EA_{IoU} and EA_{PG} for each model using the ImageNet validation set and its bounding box explanations [\[17\]](#page-16-1). We use Vanilla Gradients [\[61\]](#page-21-0) thresholded at one standard deviation

 2 <https://timm.fast.ai/>

Fig. 3: Measuring explanation alignment using multiple human explanations shows that similarly accurate models use different underlying facial features. We compare GradCAM [\[59\]](#page-20-7) explanations thresholded at 0.5 against 5 facial annotations [\[34\]](#page-17-7).

above the mean across all models and Grad-CAM [\[59\]](#page-20-7) thresholded at 0.5 on the 150 models containing convolutional layers. We compare the explanation alignment against the model's accuracy on the ImageNet validation set and its transfer learning performance on CIFAR-100 [\[32\]](#page-17-8). We perform 1-shot transfer learning via a logistic regression that takes in the models' penultimate layer embeddings and predicts the CIFAR-100 labels. We report our results in Fig. [4.](#page-12-0)

Explanation alignment differs based on model architecture. Across settings, the range of explanation alignment values differ based on model architecture. Transformers [\[67\]](#page-21-6) have lower explanation alignment scores than CNNs [\[21\]](#page-16-9). For a direct comparison, we use the same saliency method (Vanilla Gradients) to compute explanation alignment for all models, regardless of architecture. However, due to the patch-based tokenization procedure of Image Transformers [\[47\]](#page-19-4), Vanilla Gradients often highlights rectangular image regions as opposed to continuous saliency distributions we see in CNNs (Fig. [A2\)](#page-24-1). Since the model explanations have a different distribution for Transformers than CNNs, the explanation alignment scores are not directly comparable between model architectures.

Explanation alignment is sensitive to the underlying saliency method. Differences in saliency methods result in differences in explanation alignment values. Computing explanation alignment with Vanilla Gradients results in EA_{IoU} scores in the range 0–0.2, whereas with Grad-CAM scores range from 0.1–0.6. Comparing models with explanation alignment should use the same saliency method to prevent confounding differences in alignment due to the saliency method with differences in alignment due to the model's behavior. Further, it is important to select a saliency method relevant to the model and task. As we saw in the previous take-away, Vanilla Gradients produces patch-based explanations for Transformers that skews the range of explanation alignment values. This signals the

Fig. 4: We compare the explanation alignment of 195 models across saliency methods (Vanilla Gradients and Grad-CAM), explanation alignment metrics (EA_{IoU}) and EAPG), and tasks (ImageNet classification and CIFAR-100 transfer learning). In each plot, color indicates architecture type and size encodes number of model parameters.

importance of computing explanation alignment with a task-appropriate saliency method, such as a method designed specifically for Transformers [\[10,](#page-15-0) [13,](#page-15-7) [15\]](#page-15-2).

 EA_{IoU} and EA_{PG} are interchangeable for relative model comparisons. Both explanation alignment measures (EA_{IoU} and EA_{PG}) result in similar model rankings (Spearman's rank correlation coefficient $\rho = 0.902, p < 0.001$). Unlike explanation alignment's sensitivity to saliency method, the relative explanation alignment between models does not change substantially based on the underlying saliency-based alignment metric. While the absolute value EA_{IoU} and EA_{PG} measure a specific aspect of the model's alignment, they can be interchanged when measuring the relative alignment difference between models.

Accurate models can have low explanation alignment and vice versa. Confirming our prior experimental results, we find that highly accurate models can have low explanation alignment, since learning misaligned correlations can still result in correct decisions within a dataset. However, we also find that aligned models can have low task accuracy. One hypothesis for this is that spurious correlations can still occur within the object of interest. For instance, even a model that relies on pixels of the apple to predict apple could do so in unaligned ways, such as only looking at color due to a bias that all apples are red. This signals the importance of measuring explanation alignment alongside accuracy to ensure models are both correct and human-aligned.

Explanation alignment does not predict ImageNet to CIFAR-100 transferability. We would expect that models with greater explanation alignment would be better able to transfer to new domains because they have learned the same reasoning processes humans use to generalize between tasks. However, we do not find a correlation between the explanation alignment of an ImageNet model and its 1-shot learning performance on CIFAR-100. On one hand, this could suggest that while explanation alignment can reveal differences in model behavior (e.g., bias), it is not predictive of model generalizability. On the other hand, it could also be the case that explanation alignment on ImageNet is not necessary to generalize to the simple and small CIFAR-100 images which typically only contain a single ob-

ject. Future work may consider larger-scale analysis and benchmarks to measure the relationship between different types of alignment and model generalization.

5 Conclusion and Discussion

We present explanation alignment, a method to quantify the agreement between model explanations with human reasoning. Using saliency methods [\[59,](#page-20-7) [61\]](#page-21-0), we generate model explanations and human-defined ground truth from existing datasets [\[17,](#page-16-1) [34\]](#page-17-7). We aggregate the results of saliency-based alignment metrics [\[8,](#page-14-1) [71\]](#page-22-1) over many data instances to quantify the model's alignment over many decisions. Through experiments on ImageNet [\[17\]](#page-16-1), MNIST [\[18\]](#page-16-0), and CelebA [\[37\]](#page-18-3) datasets, we demonstrate that explanation alignment can reveal biases and behavioral differences between models with similar performance metrics. Our findings highlight the importance of aligning model explanations with human expectations to improve transparency, trustworthiness, and performance.

To compute explanation alignment, we leverage saliency methods to generate model explanations. Saliency methods are valuable to our computation because they quantify the importance of each image feature, making them directly comparable to human explanations that are also defined on the image pixels. However, research has demonstrated that saliency methods can generate inconsistent explanations, highlight irrelevant features, and produce misleading explanations [\[1,](#page-14-6) [6\]](#page-14-7). While explanation alignment accounts for one-off saliency mistakes by aggregating over many model decisions, future work could explore more robust saliency methods or ways to compute explanation alignment without saliency methods, such as through concept-based or counterfacutal explanations.

Relatedly, explanation alignment requires human explanations in the form of annotations of important image regions. In our experiments, we found that many research datasets have associated human explanations [\[17,](#page-16-1) [34\]](#page-17-7) or that explanations can be derived from existing metadata [\[18,](#page-16-0) [37\]](#page-18-3). However, in settings where human explanations can not be derived, image segmentation [\[40\]](#page-18-7) or object localization [\[66\]](#page-21-7) models could identify important image regions as human-like explanations. Further, defining a human explanation is inherently subjective, and, as we saw in Sec. [4.3,](#page-9-0) there may exist many possible human explanations for a given decision. As a result, future work could explore alternate representations for human explanations, such as human studies to understand how humans select and combine features to make their decisions.

Successful use of explanation alignment metrics suggests incorporating them into model training to enforce explanation alignment during development. While traditional training procedures emphasize correctness, explanation alignment provides an opportunity to update model parameters based on their reasoning processes and alignment with human reasoning. Incorporating these metrics could enable developers to enhance models beyond accuracy benchmarks, emphasizing the importance of how the model made its decision. Such models would be not only trustworthy and reliable but could improve robustness to new and unseen data.

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A Appendix

A.1 Additional Examples

Fig. [A1](#page-23-0) and Fig. [A2](#page-24-1) illustrate the experimental setup used to evaluate the explanation alignment between model predictions and human expectations in ImageNet image classification tasks, providing visual context for the comparison of models with different model architectures and saliency methods.

Fig. A1: Explanation alignment reveals that similarly accurate ImageNet models have different model reasoning. Despite each model (convnext_tiny, regnet_x_3_2_gf, and regnet_y_1_6_gf) achieving 81 – 82% accuracy, their EA_{IoU} and EA_{PG} vary by 20%, reflecting the differences in human alignment visible in their saliency maps.

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Fig. A2: The saliency maps of cait_s24_384 and resmlp_12_distilled_224 show more scattered and noisy patterns due to their transformer-based architecture, whereas resnet269e and tf_mobilenetv3_small_minimal_100 exhibit more continuous maps, due to their convolutional network designs. Interestingly, tf_mobilenetv3_small_minimal_100 yields higher mean explanation alignment despite less focused saliency maps, likely because the human explanation annotations in ImageNet tend to cover larger regions. This highlights the impact of the choice of saliency method, model architecture, and human explanations on measuring explanation alignment.

A.2 Model Training Details

In this paper, we conduct experiments on three distinct datasets: ImageNet [\[17\]](#page-16-1), MNIST [\[18\]](#page-16-0), and CelebA [\[37\]](#page-18-3), using pretrained models and custom architectures to evaluate their performance across different image classification tasks. These experiments are executed on a GPU-enhanced, high-performance Power 9 system, featuring 64 nodes with 1TB memory each, equipped with four NVIDIA

V100 32GB GPUs per node, interconnected by NVLink2 for high-speed GPU communication and a 100Gb/s Infiniband network for cluster connectivity.

ImageNet We evaluate pretrained ImageNet [\[17\]](#page-16-1) models provided by Py-Torch [\[49\]](#page-19-5). Among them, we use three CNN models: ConvNeXt Tiny, Reg-NetX 3.2GF, and RegNetY 1.6GF. ConvNeXt, designed by updating a standard ResNet to mimic a Vision Transformer (ViT), results in similar accuracy to ViT but maintains the simplicity of standard ConvNets [\[38\]](#page-18-8). RegNet, a network design space rather than a single architecture, presents a variety of model architectures characterized by distinct parameters [\[51\]](#page-19-6). The key difference between RegNetX and RegNetY models is the inclusion of the Squeeze and Excitation layer in RegNetY.

MNIST To perform the experiment in Sec. [4.1,](#page-5-0) we design a neural network architecture for image classification. This architecture processes 3-channel input images through two convolutional layers with ReLU activations, incorporates max pooling and dropout layers to reduce overfitting, and concludes with two fully connected layers utilizing softmax activation for class probability output. This custom model is trained on a modified version of the MNIST dataset, described in Sec. [4.1,](#page-5-0) over four epochs with negative log likelihood loss. With the batch size of 64, the training of each epoch took approximately one minute, totaling four minutes per model.

CelebA We use the pretrained ImageNet [\[17\]](#page-16-1) pretrained ResNet50 [\[27\]](#page-17-6) model for image recognition. ResNet50 model, a part of the Residual Network (ResNet) series, is a deep convolutional neural network (CNN) architecture, with 50 layers in the network. The dataset is divided into biased and unbiased sets based on hair color and smiling attributes, further described in Sec. [4.2](#page-7-0) for training and testing. Models are trained over five epochs using cross-entropy loss, with a batch size of 128. Each epoch took, in average, 16 minutes, totaling in 80 minutes per model.

A.3 Metric Computation

Saliency Method and Implementation After comparing different existing saliency methods, we use Grad-CAM [\[59\]](#page-20-7) and Vanilla Gradients [\[61\]](#page-21-0) for their effectiveness in producing representative explanations of model reasoning. Grad-Cam excels at localizing relevant areas in the image for the model's decision, whereas Vanilla Gradient demonstrate the sensitivity of each pixel on its decision. We use the publicly available implementations of these saliency methods from the Shared Interest paper [\[8\]](#page-14-1).

Thresholding Technique For Grad-CAM, we select a threshold of 0.5, chosen after observing a range in average saliency values across models, which varied from nearly zero to almost one. This decision is validated through analyses across diverse settings, including differences in ground truth and saliency map sizes. This thresholding technique produces a consistent and balanced representation of the model's explanation across these settings.

For Vanilla Gradients, we apply a threshold set at one standard deviation above the mean, chosen through our analysis of saliency maps' focus and specificity. Due to its tendency to be noisier, thresholding based on a single value is insufficient. Also, thresholding at the mean results in broad, unfocused maps lacking in detailed model explanation, whereas thresholding at two standard deviations above the mean produced overly narrow map that are sometimes too limited for effective metric evaluation. The chosen threshold produces a balanced representation, capturing the essence of model explanations in a way that is both focused and sufficiently detailed.

List of 195 models used in experiments

- 1. adv_inception_v3
- 2. bat_resnext26ts
- 3. beit_base_patch16_224
- 4. beit_base_patch16_384
- 5. botnet26t_256
- 6. cait_s24_224
- 7. cait_s24_384
- 8. cait_s36_384
- 9. cait_xs24_384
- 10. cait_xxs24_224
- 11. cait_xxs24_384
- 12. cait_xxs36_224
- 13. cait_xxs36_384
- 14. coat_lite_mini
- 15. coat_lite_small
- 16. coat_lite_tiny
- 17. coat_mini
- 18. coat_tiny
- 19. convit_base
- 20. convit_small
- 21. convit_tiny
-
- 22. convmixer_1024_20_ks9_p14
- 23. convnext_base
- 24. cspdarknet53
- 25. cspresnet50
- 26. cspresnext50
- 27. deit_base_patch16_224
- 28. densenet121
- 29. dla60
- 30. dla60_res2net

31. dla60_res2next

- 32. dla60x
- 33. dla60x_c
- 34. dm_nfnet_f2
- 35. dpn68
- 36. efficientnetv2_rw_t
- 37. ens_adv_inception_resnet_v2
- 38. ese_vovnet19b_dw
- 39. ese_vovnet39b
- 40. fbnetc_100
- 41. fbnetv3_d
- 42. fbnetv3_g
- 43. gc_efficientnetv2_rw_t
- 44. gcresnet33ts
- 45. gcresnet50t
- 46. gcresnext26ts
- 47. gcresnext50ts
- 48. gernet_l
- 49. gernet_m
- 50. gernet_s
- 51. ghostnet_100
- 52. gluon_inception_v3
- 53. gluon_resnet101_v1b
- 54. gluon_resnet152_v1b
- 55. gluon_resnet152_v1c
- 56. gluon_resnet152_v1d
- 57. gluon_resnet152_v1s
- 58. gluon_resnet18_v1b
- 59. gluon_resnet34_v1b
- 60. gluon_resnet50_v1b
- 61. gluon_resnet50_v1c
- 62. gluon_resnet50_v1d
- 63. gluon_resnet50_v1s
- 64. gluon_resnext101_32x4d
- 65. gluon_senet154
- 66. gluon_seresnext101_32x4d
- 67. gmixer_24_224
- 68. gmlp_s16_224
- 69. halo2botnet50ts_256
- 70. halonet26t
- 71. haloregnetz_b
- 72. hardcorenas_a
- 73. hrnet_w18
- 74. ig_resnext101_32x16d
- 75. inception_resnet_v2
- 76. inception_v3

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77. jx_nest_base 78. lambda_resnet26rpt_256 79. lamhalobotnet50ts_256 80. lcnet_050 81. legacy_senet154 82. legacy_seresnet101 83. legacy_seresnext101_32x4d 84. mixer_b16_224 85. mixnet_l 86. mnasnet_100 87. regnety_080 88. regnety_120 89. regnety_160 90. regnety_320 91. regnetz_b16 92. regnetz_c16 93. regnetz_d32 94. regnetz_d8 95. regnetz_e8 96. repvgg_a2 97. repvgg_b0 98. repvgg_b1 99. repvgg_b1g4 100. repvgg_b2 101. repvgg_b2g4 102. repvgg_b3 103. repvgg_b3g4 104. res2net101_26w_4s 105. res2net50_14w_8s 106. res2net50_26w_4s 107. res2net50_26w_6s 108. res2net50_26w_8s 109. res2net50_48w_2s 110. res2next50 111. resmlp_12_224 112. resmlp_12_distilled_224 113. resmlp_24_224 114. resmlp_24_distilled_224 115. resmlp_36_224 116. resmlp_36_distilled_224 117. resmlp_big_24_224 118. resmlp_big_24_224_in22ft1k 119. resmlp_big_24_distilled_224 120. resnest101e 121. resnest14d 122. resnest200e

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- 123. resnest269e
- 124. resnest26d
- 125. resnest50d
- 126. resnest50d_1s4x24d
- 127. resnest50d_4s2x40d
- 128. resnet101
- 129. resnet101d
- 130. resnet152
- 131. resnet152d
- 132. resnet18
- 133. resnet18d
- 134. resnet200d
- 135. resnet26
- 136. resnet26d
- 137. resnet26t
- 138. resnet32ts
- 139. resnet33ts 140. resnet34
-
- 141. resnext26ts
- 142. resnext50_32x4d
- 143. sebotnet33ts_256
- 144. sehalonet33ts
- 145. selecsls60b
- 146. semnasnet_075
- 147. semnasnet_100
- 148. seresnet152d
- 149. seresnet33ts
- 150. seresnet50
- 151. seresnext26d_32x4d
- 152. seresnext26t_32x4d
- 153. seresnext26ts
- 154. seresnext50_32x4d
- 155. skresnet18
- 156. skresnet34
- 157. skresnext50_32x4d
- 158. spnasnet_100
- 159. ssl_resnet18
- 160. ssl_resnet50
- 161. ssl_resnext101_32x16d
- 162. ssl_resnext101_32x4d
- 163. ssl_resnext101_32x8d
- 164. ssl_resnext50_32x4d
- 165. swin_base_patch4_window12_384
- 166. swin_base_patch4_window7_224
- 167. swsl_resnet18
- 168. swsl_resnext101_32x4d

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- 169. swsl_resnext101_32x8d
- 170. swsl_resnext50_32x4d
- 171. tf efficientnet b0
- 172. tf_efficientnet_b0_ap
- 173. tf_efficientnet_b0_ns
- 174. tf efficientnet b1
- 175. tf_efficientnet_b1_ap
- 176. tf_efficientnet_b1_ns
- 177. tf_efficientnet_b2
- 178. tf_efficientnet_b2_ap
- 179. tf_efficientnet_b2_ns
- 180. tf_efficientnet_b3
- 181. tf_efficientnet_b3_ap
- 182. tf_efficientnet_b3_ns
- 183. tf_efficientnet_b4
- 184. tf_inception_v3
- 185. tf_mixnet_s
- 186. tf_mobilenetv3_small_minimal_100
- 187. tinynet_a
- 188. tnt_s_patch16_224
- 189. tv_resnet50
- 190. tv resnext50 $\,$ 32x4d
- 191. twins_pcpvt_base
- 192. twins_svt_base
- 193. vgg16
- 194. vgg16_bn
- 195. visformer_small